

**Micro-RDC**

Microelectronics Research Development Corporation



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# **New Test and Analysis Approaches for SEE Characterization**

**GOMACTech-10**

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- ❑ **Describe the Milli-Beam™ raster scanning technique**
  - Most recent test advance by Micro-RDC
  - New technique to raster scan complex integrated circuits
  - Spatial resolutions easily varied between 10  $\mu\text{m}$  and 500  $\mu\text{m}$
  - Automated calibration, scanning, and data acquisition
  - Provides surface plot of IC error cross section as function of position
  
- ❑ **Show photos of the actual apparatus**
  - As presently installed at the Berkeley 88-inch cyclotron
  
- ❑ **Present examples of recent measurements**
  - SRAM scan
  - DSET propagation chain scan
  - PLL loss of lock raster scan



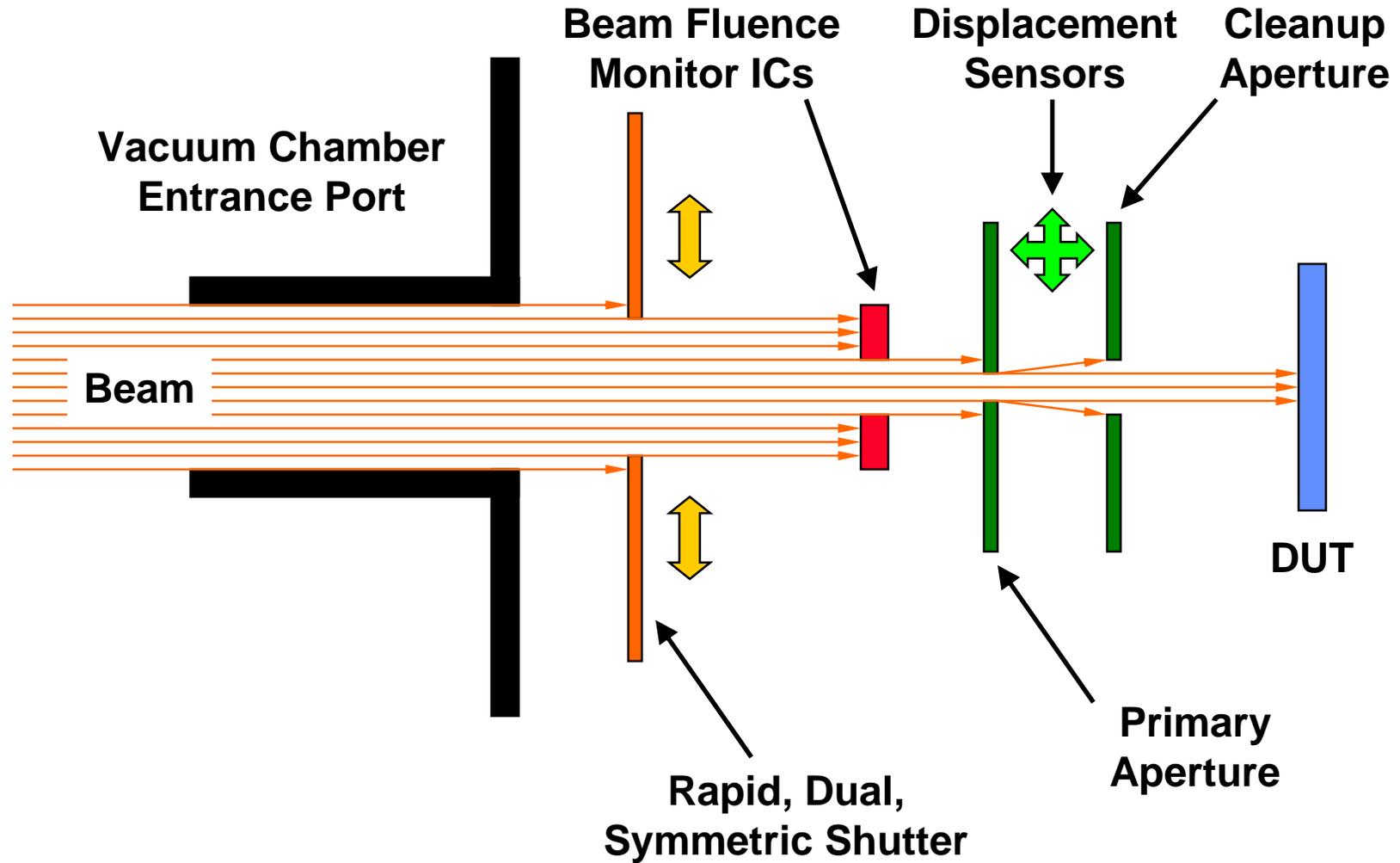
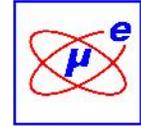
# Milli-Beam Overview and Features

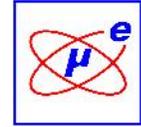


- ❑ **Precise collimation for use at the LBL cyclotron**
  - New hardware and software to raster scan complex ICs
  - Achieve spatial resolutions between 10  $\mu\text{m}$  and 500  $\mu\text{m}$
- ❑ **Hardware**
  - Primary square aperture (2-orthogonal slits) stepped  $<1 \mu\text{m}$  precision
  - Secondary scattering cleanup aperture controlled from second stage
  - Displacement sensors provide error feedback signal for corrections
- ❑ **Software**
  - Computes coordinate transformations, sets beam position, controls run
  - Provide FPGA test board with positions for inclusion in error message
- ❑ **Independent ICs for beam characterization and dosimetry**
  - Homogeneous RAM for location and intensity profile measurement
  - Specially designed Beam monitor ICs placed upstream of aperture
  - At preset fluences: Stop data acquisition, step apertures, update FPGA test board with new position, resume data acquisition



# Milli-Beam Schematic





# Physical Considerations

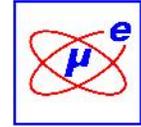
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- ❑ Displacement and rotation of DUT w.r.t. calibration SRAM
- ❑ SRAM Y-axis rotation w.r.t. Milli-Beam Y-actuator
- ❑ Non-orthogonally of Milli-Beam X and Y actuators
- ❑ Berkeley Stage Y-axis rotation w.r.t. Milli-Beam Y-actuator<sup>†</sup>
- ❑ Non-orthogonally of Berkeley X and Y actuators<sup>†</sup>
- ❑ Dimensional scaling of each actuator<sup>†</sup>

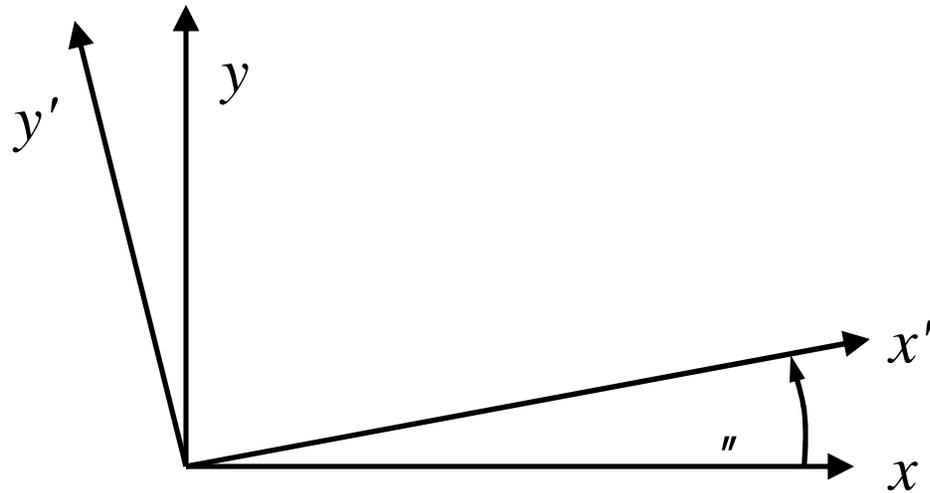
<sup>†</sup> Only if need to move Berkeley Stage to bring DUT into Milli-Beam Range



# Milli-Beam Coordinate Transformations (1 of 4)



## □ Simple Rotation



$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

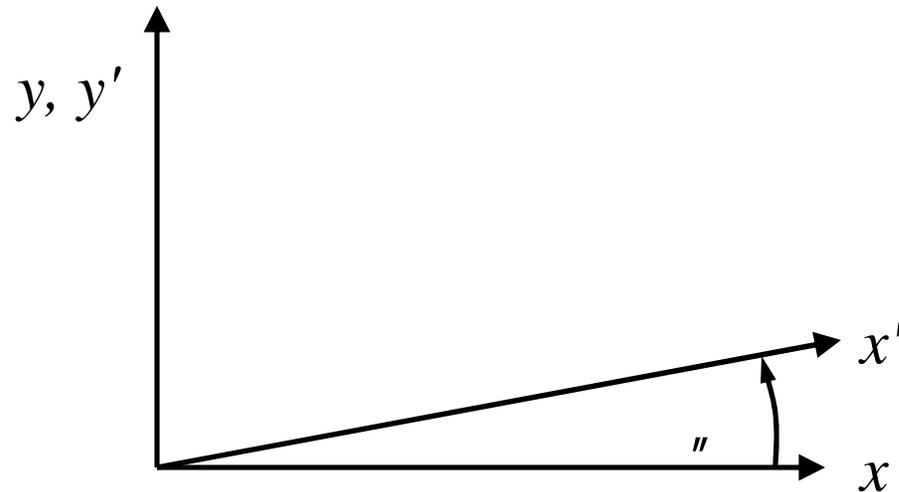
$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \cdot \begin{pmatrix} x' \\ y' \end{pmatrix}$$



# Milli-Beam Coordinate Transformations (2 of 4)



## □ Non-Orthogonally Transformations

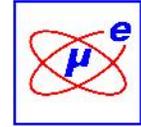


$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{bmatrix} 1/\cos \theta & 0 \\ -\tan \theta & 1 \end{bmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

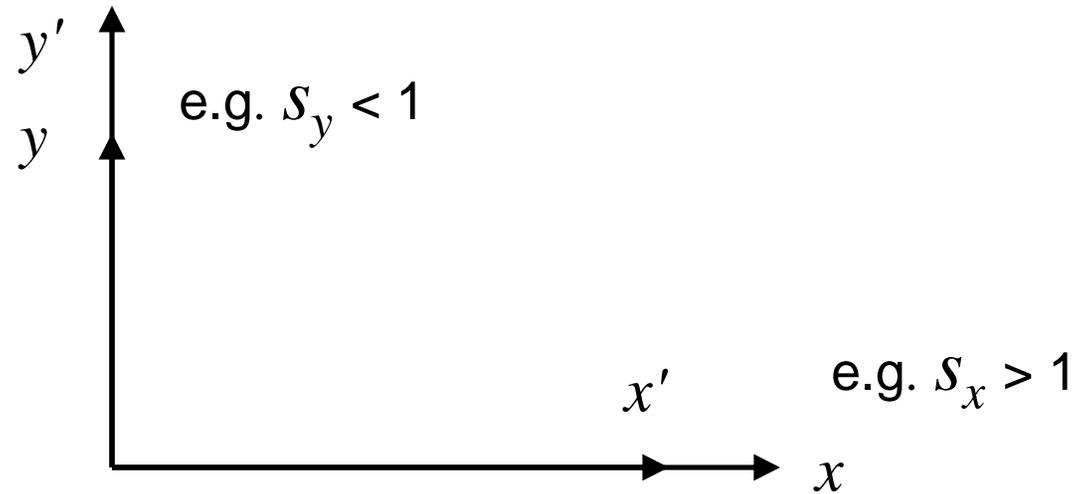
$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{bmatrix} \cos \theta & 0 \\ \sin \theta & 1 \end{bmatrix} \cdot \begin{pmatrix} x' \\ y' \end{pmatrix}$$



# Milli-Beam Coordinate Transformations (3 of 4)



## Axis Scaling

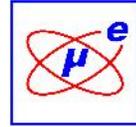


$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{bmatrix} s_x & 0 \\ 0 & s_y \end{bmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

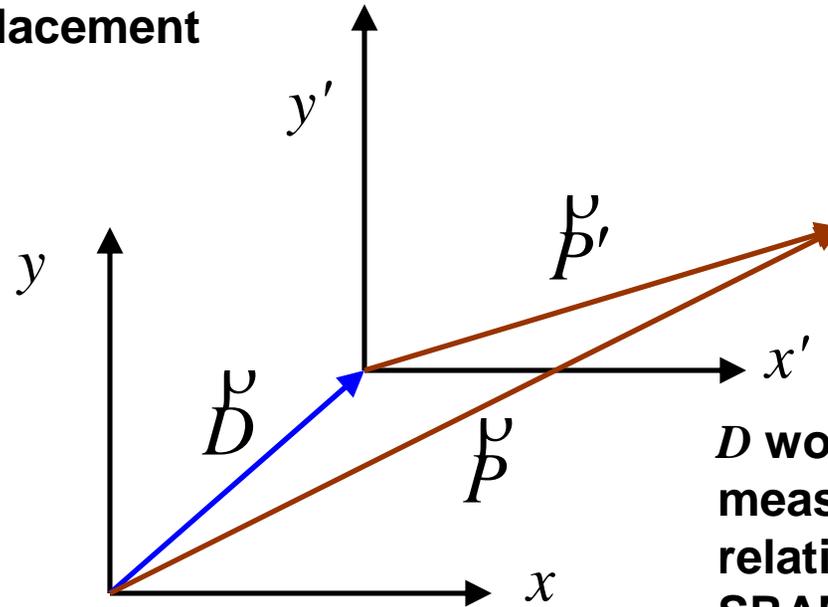
$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{bmatrix} 1/s_x & 0 \\ 0 & 1/s_y \end{bmatrix} \cdot \begin{pmatrix} x' \\ y' \end{pmatrix}$$



# Milli-Beam Coordinate Transformations (4 of 4)



## □ Simple Displacement

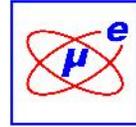


**$D$  would typically measure DUT location relative to calibration SRAM location**

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} X_D \\ Y_D \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x' \\ y' \end{pmatrix} + \begin{pmatrix} X_D \\ Y_D \end{pmatrix}$$





# Final Form of the Transformation

- Transformation to compute Milli-Beam raster scan movements

$$\begin{pmatrix} x_m \\ y_m \end{pmatrix} = \begin{matrix} O \\ \begin{bmatrix} \times & \times \\ \times & \times \end{bmatrix} \end{matrix} \cdot \begin{matrix} R^{-1} \\ \begin{bmatrix} \times & \times \\ \times & \times \end{bmatrix} \end{matrix} \cdot \left\{ \begin{matrix} R_D^{-1} \\ \begin{bmatrix} \times & \times \\ \times & \times \end{bmatrix} \end{matrix} \cdot \begin{pmatrix} x_{dut} \\ y_{dut} \end{pmatrix} + \begin{pmatrix} x_D \\ y_D \end{pmatrix} \right\}$$
  

$$\begin{pmatrix} x_D \\ y_D \end{pmatrix} = \begin{pmatrix} x_{D_o} \\ y_{D_o} \end{pmatrix} + \begin{matrix} R_{\text{''}} \\ \begin{bmatrix} \times & \times \\ \times & \times \end{bmatrix} \end{matrix} \cdot \begin{matrix} R_{\text{[}}^{-1} \\ \begin{bmatrix} \times & \times \\ \times & \times \end{bmatrix} \end{matrix} \cdot \begin{matrix} O_{\text{[}}^{-1} \\ \begin{bmatrix} \times & \times \\ \times & \times \end{bmatrix} \end{matrix} \cdot \begin{matrix} S_{\text{[}} \\ \begin{bmatrix} \times & \times \\ \times & \times \end{bmatrix} \end{matrix} \cdot \begin{pmatrix} ux_b \\ uy_b \end{pmatrix}$$

- '' → SRAM w.r.t. Milli-Beam;      D → DUT w.r.t. SRAM
- { → Berkeley w.r.t. Milli-Beam;      b → Berkeley stage movement

- Inverse transformation used to compute DUT location, along with an estimate of the variance, for each Milli-Beam raster position



# Beam Fluence Monitor



## □ Four special ICs

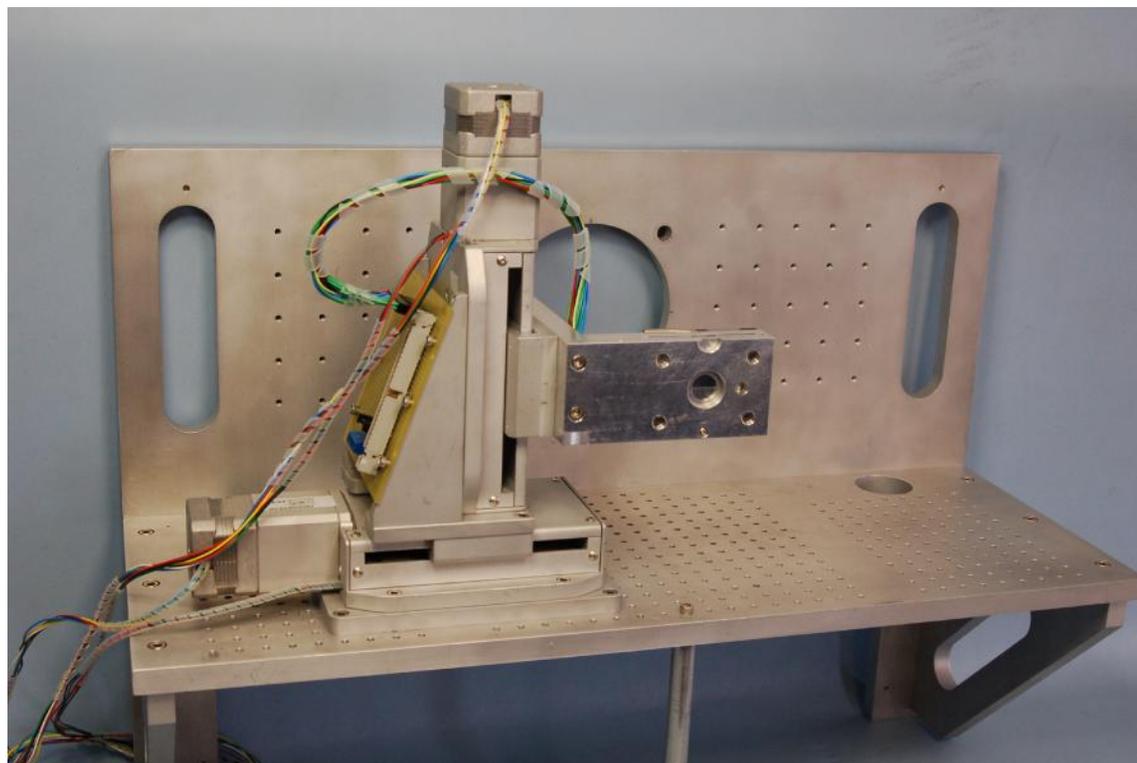
- Mounted just upstream of the Milli-Beam Primary Aperture
- Incorporates several chains of RS flip-flops
- Electrically selectable cross section
- Extremely small dead time

## □ Calibrated to an accuracy of better than 1%

- Independent of the Berkeley scintillator system
- Aperture of known size (as measured on a 90 nm SRAM)
- Particle detector counts individual heavy-ions through aperture
- Beam monitor IC events measured as a function of LET



# Complete Milli-Beam Assembly



**Micro-RDC**

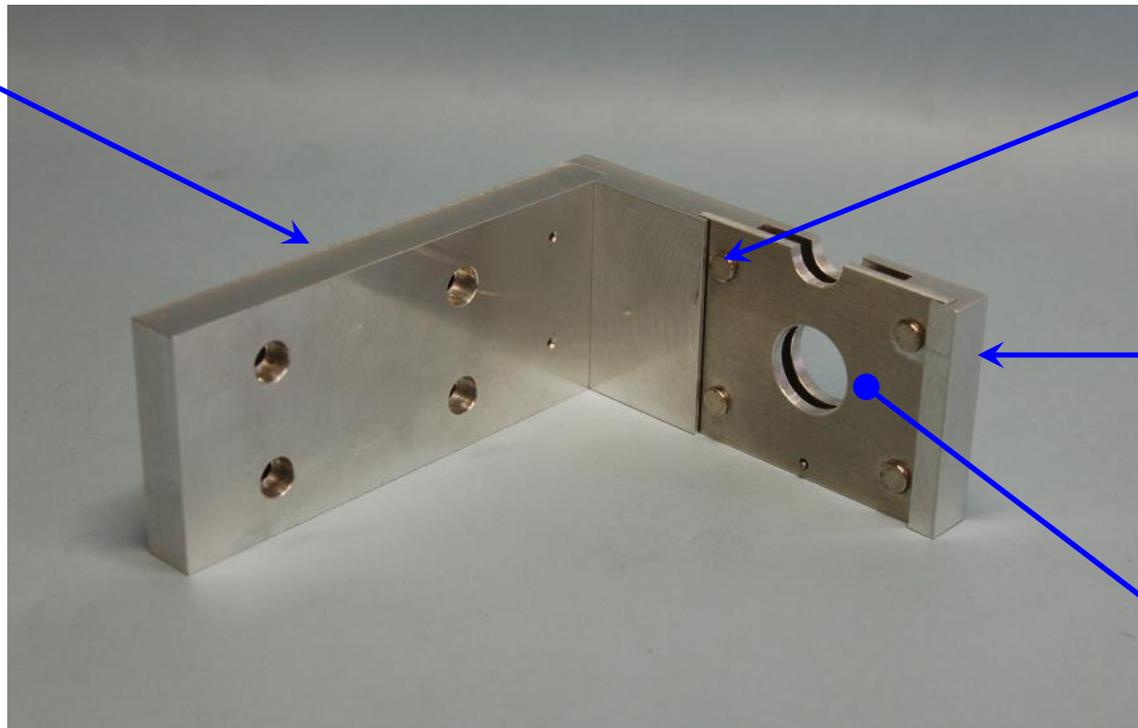
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# Aperture Mounting Assembly



Bracket  
to Mount  
to Stage



Neodymium  
Magnets (4)

Slit Holder

Pressure  
Plate

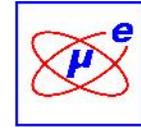


**Micro-RDC**

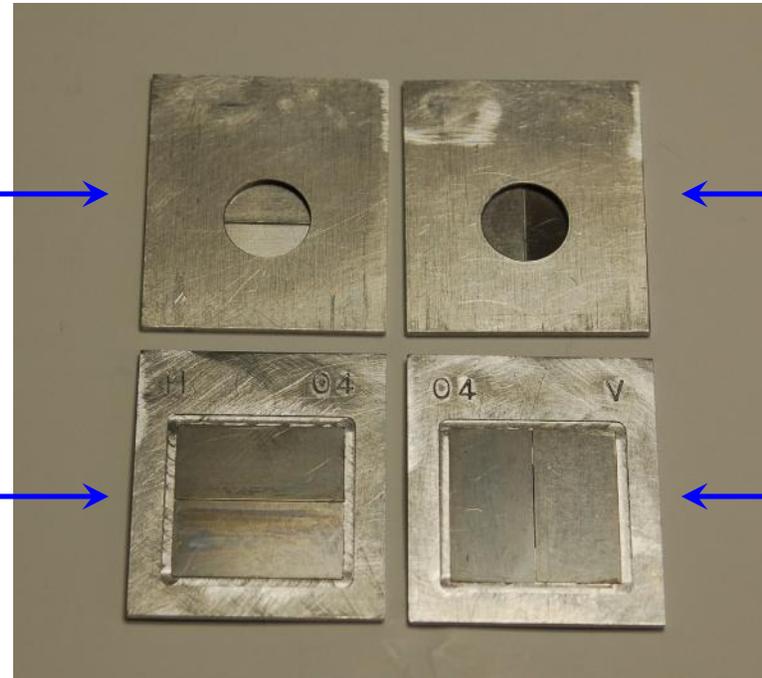
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# Aperture Construction



Outside View  
Horizontal Slit



Outside View  
Vertical Slit



Inside View  
Horizontal Slit



Inside View  
Vertical Slit



Fold to Assemble:

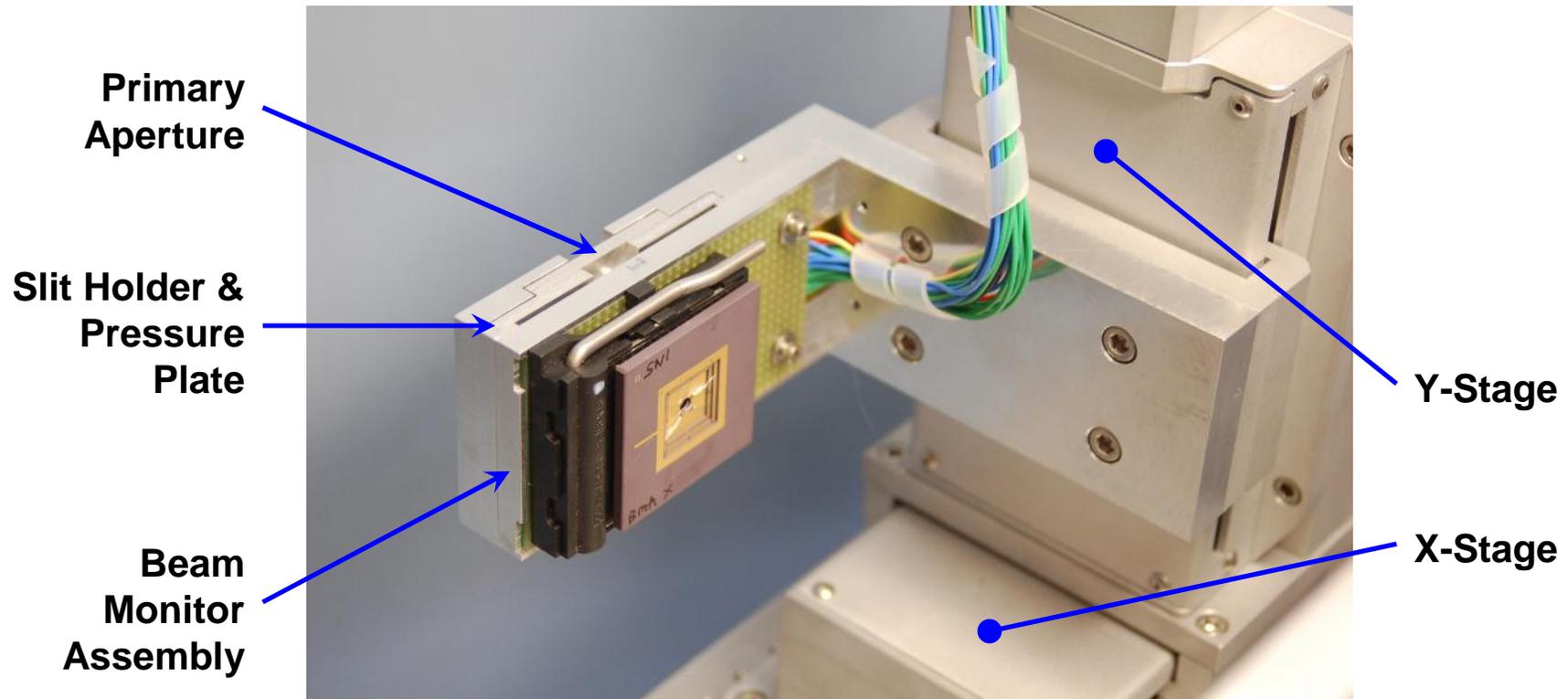
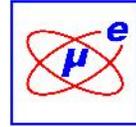


**Micro-RDC**

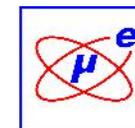
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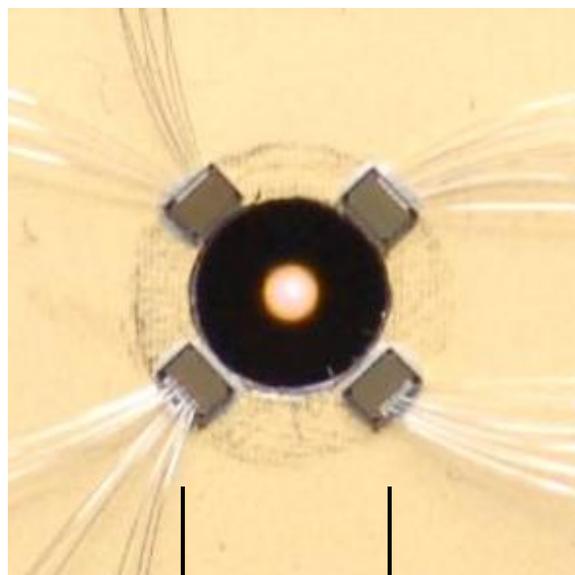
# Beam Monitor in Relation to Primary Aperture



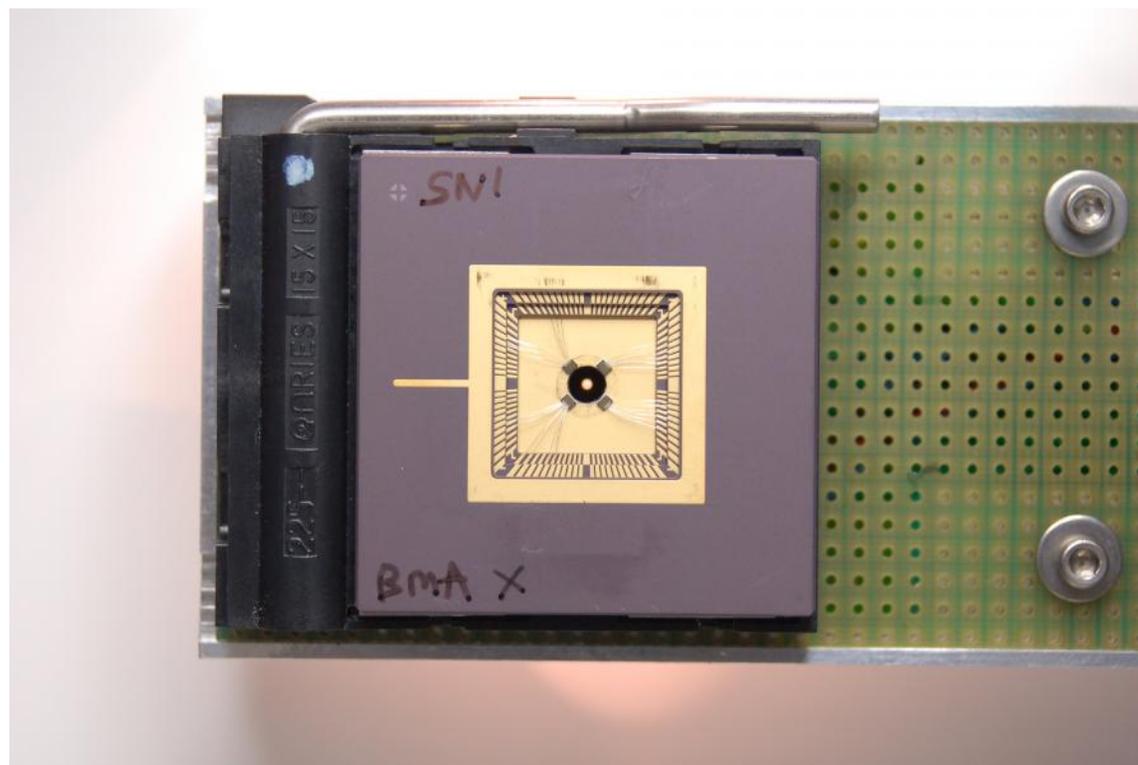
# View as Seen by the Heavy-Ion Beam



Zoomed View of Die



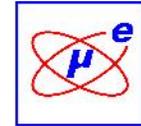
3.0 mm



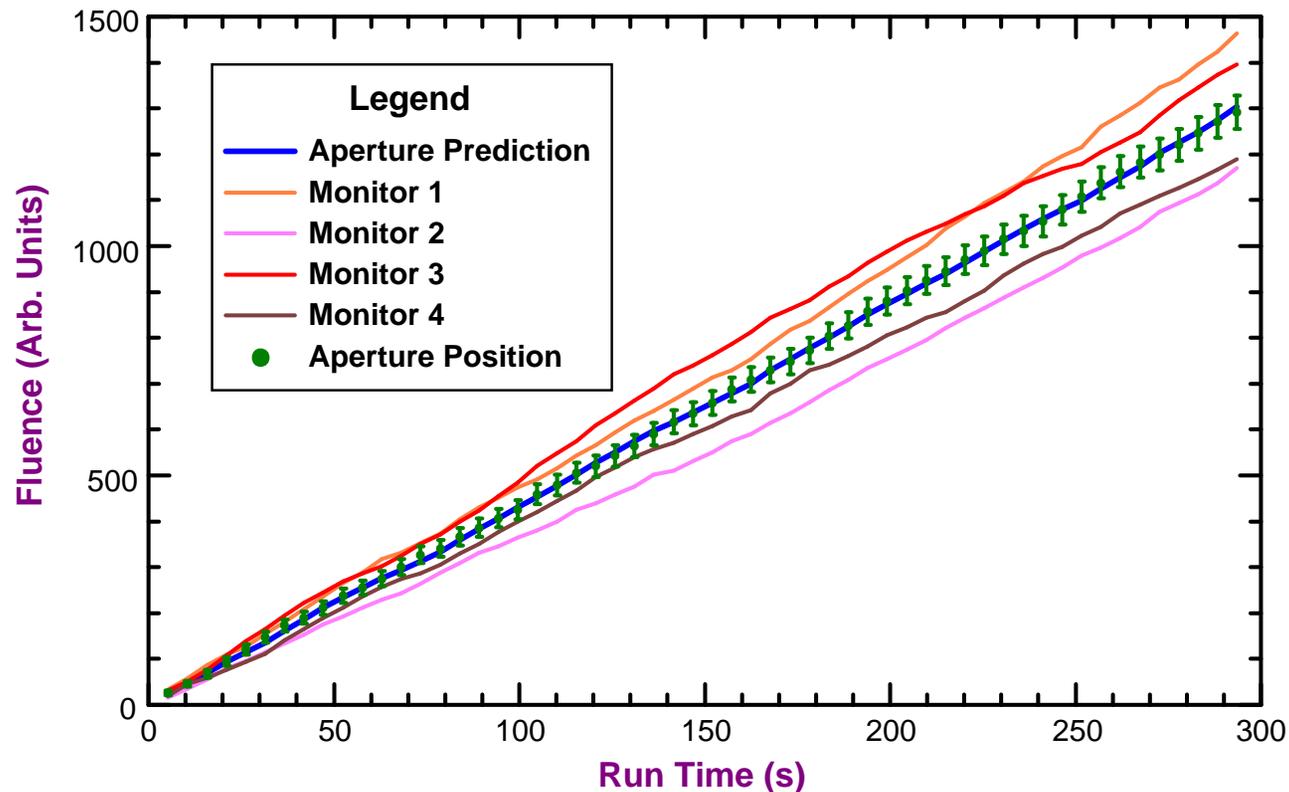
PGA, ZIF Socket, PERC Board



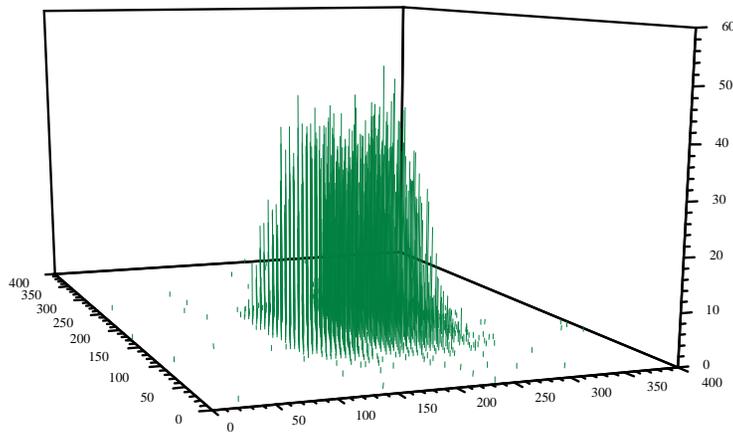
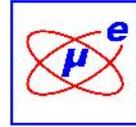
# Beam Fluence Monitor Accuracy



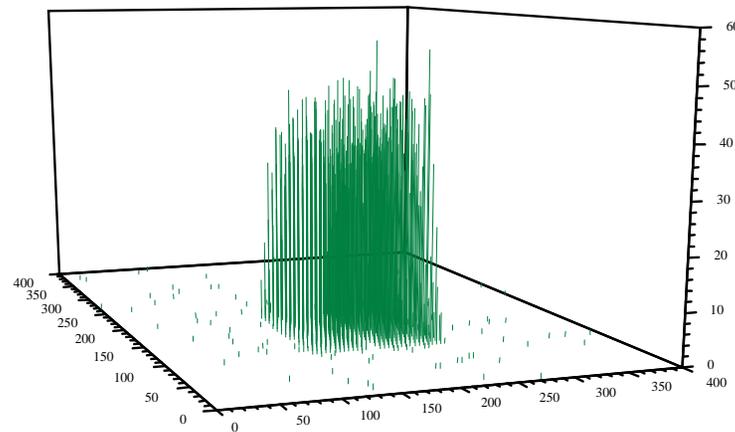
- Average the 4 monitor chip counts to predict beam flux at aperture



# Milli-Beam Intensity Profile Measurement



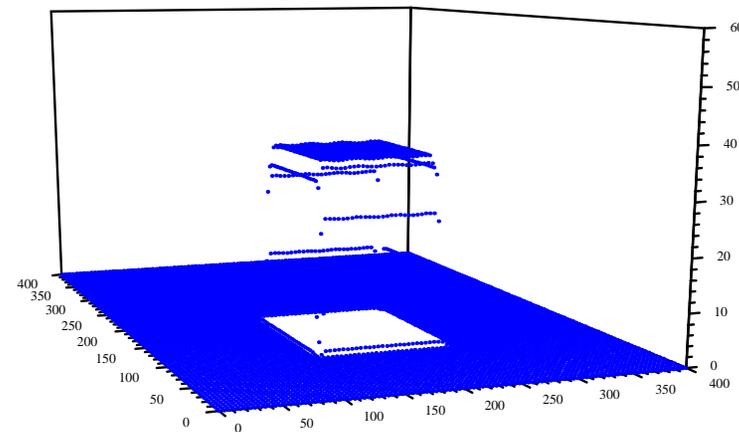
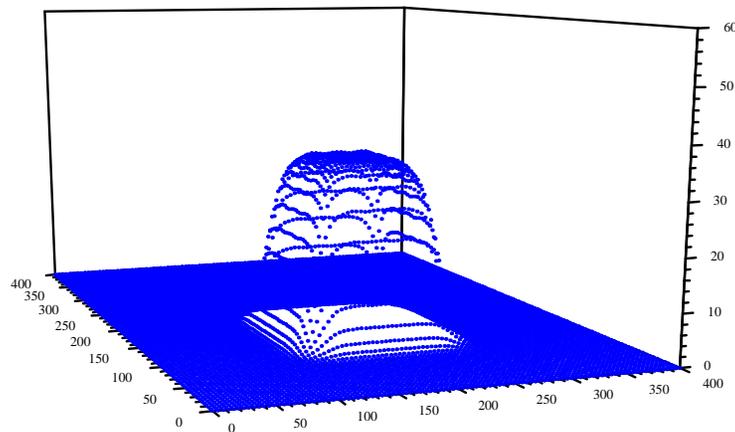
- 100  $\mu\text{m}$  square aperture
- Located 40 cm to SRAM
- Edge washout due to angular spread



- 100  $\mu\text{m}$  square aperture
- Located 5 cm to SRAM
- Sharper edge definition



# LSQ Fits to the Intensity Profile Function



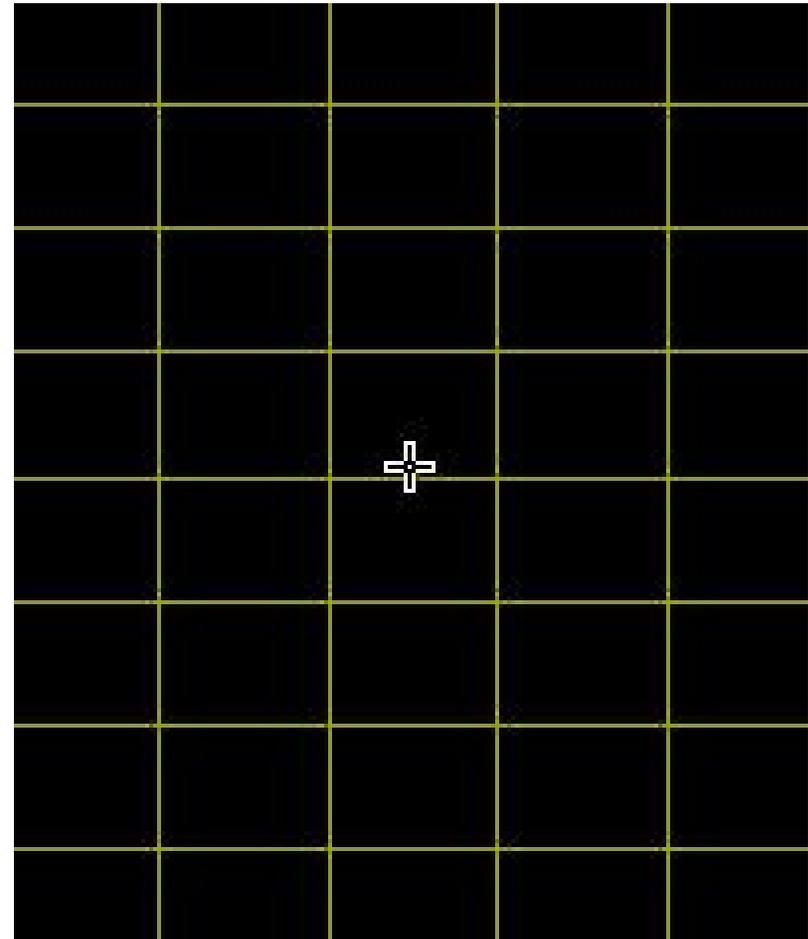
- ❑ 2-d Convolution of a Gaussian product  $z(x) \cdot z(y)$  with an x-y-z box
- ❑ Center, width, length of aperture determined to  $< 1 \mu\text{m}$  accuracy
- ❑ Gaussian  $\dagger_x$  and  $\dagger_y$  determined to  $< 0.1 \mu\text{m}$  accuracy
- ❑  $\dagger$  values again match distance times tangent of  $0.0025^\circ$
- ❑  $\dagger$  at 5 cm distance measured to be  $\sim 2 \mu\text{m}$  in x and y directions





# Example of a Raster Scan

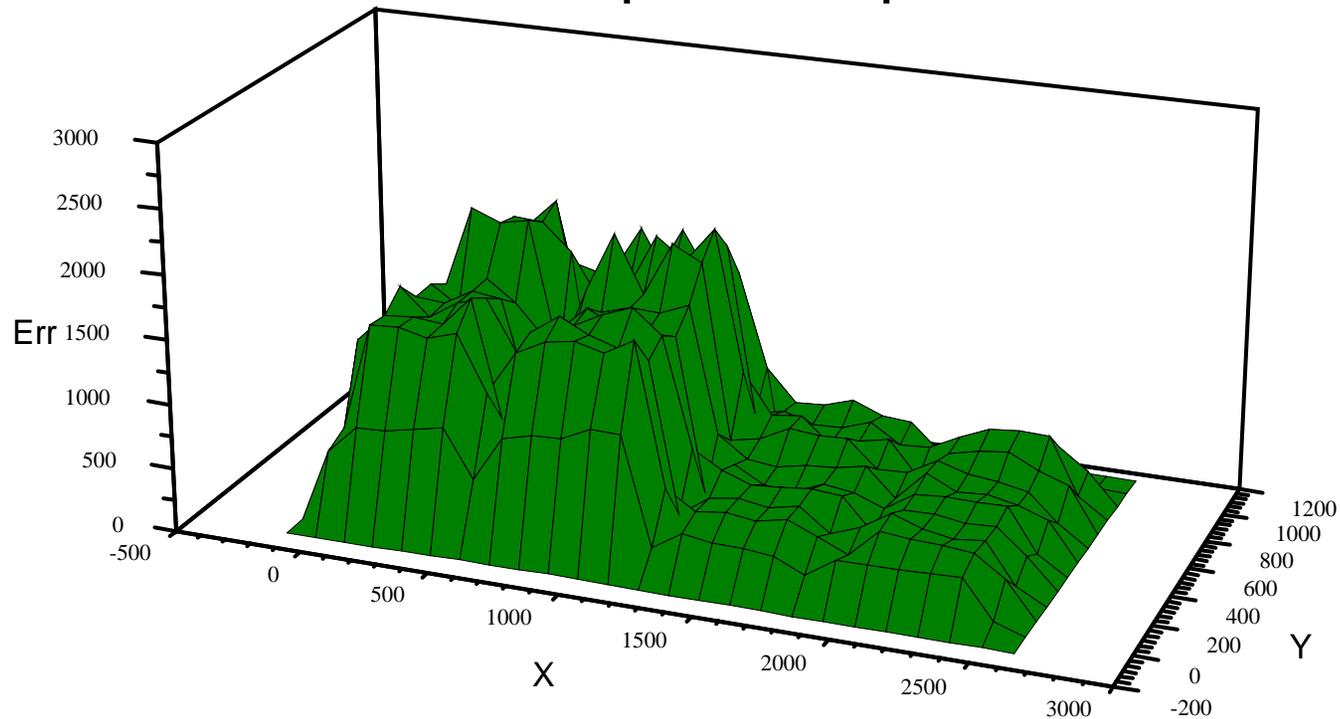
- ❑ 114  $\mu\text{m}$  x 101  $\mu\text{m}$  aperture
  - As determined from LSQ fit
  
- ❑ 5 cm from SRAM
  
- ❑  $\gg 1 \times 10^6$  Ar ions/( $\text{cm}^2\text{-sec}$ )
  - 10x normal beam intensity
  
- ❑ Use aperture size for step size
  - $U_x$  step = 114  $\mu\text{m}$
  - $U_y$  step = 101  $\mu\text{m}$
  
- ❑ Scan in a serpentine pattern
  - ~1.5 seconds/step
  - ~300 errors at each position

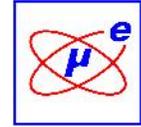


# SRAM Raster Scan Data Example



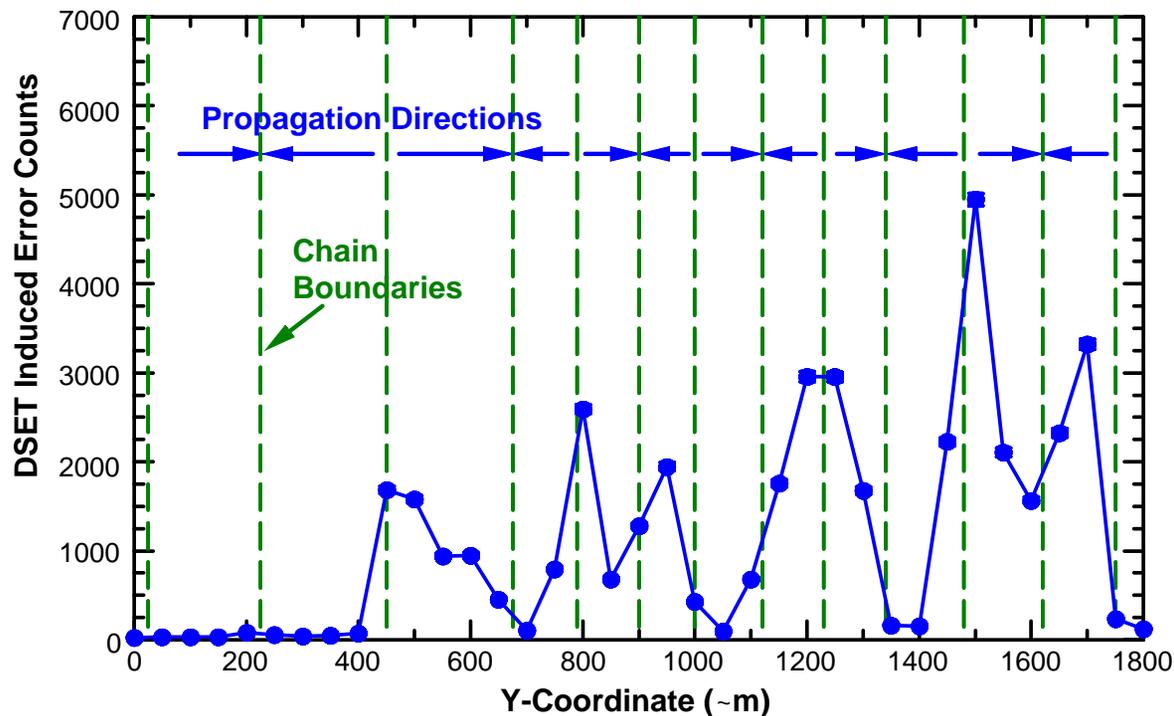
- Scan an SRAM on one of our earlier test chips
  - Two different cell designs – hardened layout on right half
  - Decode locations clearly seen in center of each array
  - Variations outside of statistical uncertainties due to beam fluctuations
  - Demonstrates the need to perform independent fluence monitoring





# Propagation Chain Slit Scan Example

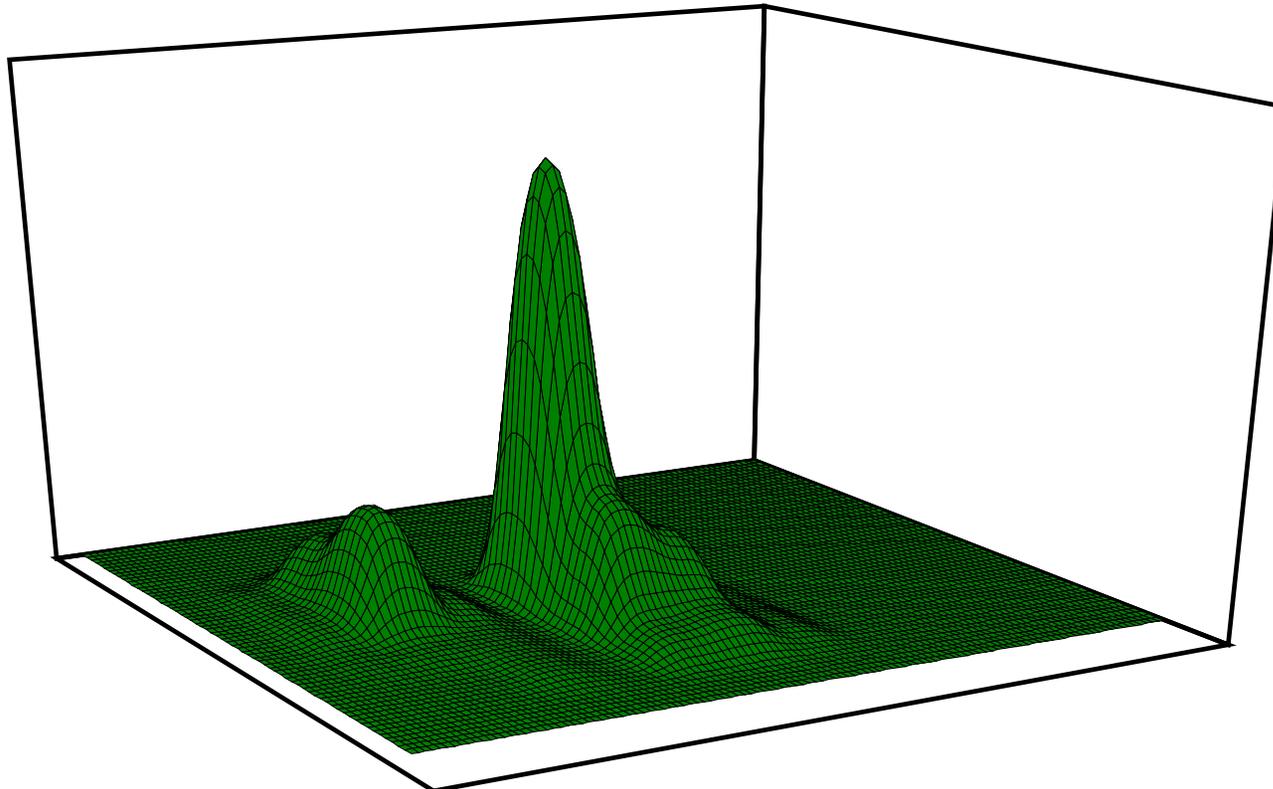
- Scan a clocked prop-chain test circuit from a DSET test chip
  - 12 different chains, propagate in y direction along an x serpentine
  - Scan a 50  $\mu\text{m}$  wide slit in 50  $\mu\text{m}$  steps along y-direction
  - Pulse broadening can be clearly seen from the data



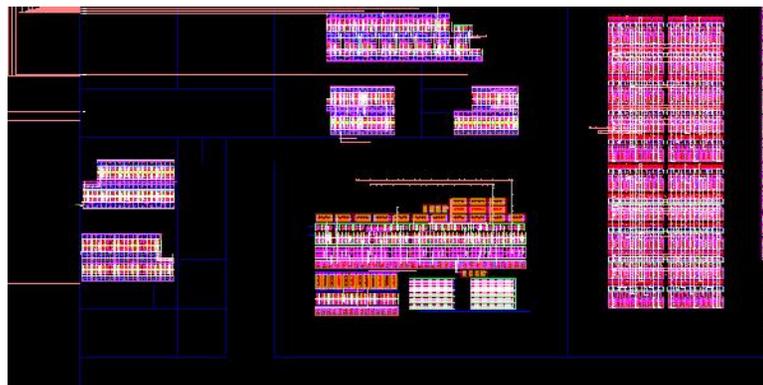
# Raster Scan of a Commercial PLL Design



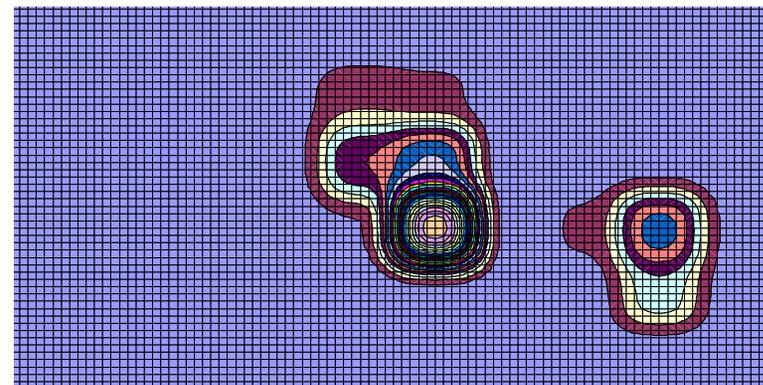
- Scan a 100  $\mu\text{m}$  square beam over the PLL circuitry
  - Better approach than trying to test standalone circuit components
  - Monitor lock signal and measure recovery time
  - Correlate observed errors to specific circuits (CP, VCO, PSD, /N,  $\hat{M}$ )



# Correlate PLL Errors to Physical Layout



Design Layout



Milli-Beam Error Contours



# Summary

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- ❑ **New test methods**
  - Full characterization of SRAM MBUs
  - True 90° heavy-ion irradiation
  - Accurate Milli-Beam raster scanning
- ❑ **Versatile data acquisition system**
  - FPGA-based mother board with inexpensive daughter cards
  - VHDL test programs to record detailed descriptions of each error
  - LabView user interfaces to control raster scans and provide real-time visualization
- ❑ **Test specific data analysis**
  - Perl scripts to parse and post-process data log files
  - Reduced data readied for graphical display and least squares fitting
  - Proper treatment of data uncertainties
  - Curvature matrix based least squares parameter extraction
  - Extraction of parameter variance
  - Correct propagation of errors when using extracted parameters

